Underwater Robotic Technology to Manage Marine Contamination



PROBLEM:

Marine Contamination



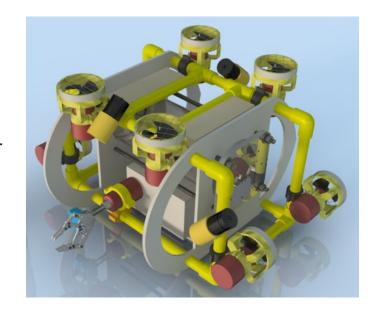
(above): Gulf of Mexico Oil Spill

- Oil spills
- Containers falling off cargo ships
- Plastic man-made debris



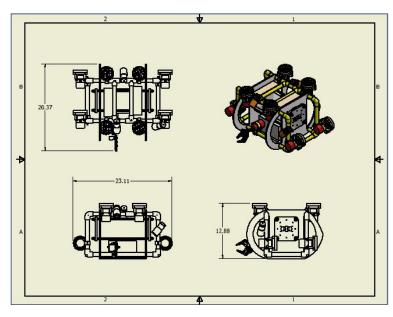
OUR SOLUTION

- Economical, efficient ROV
 - Remotely Operated Vehicle (ROV)
- Easy and intuitive control for operator
- Key Features: Custom-built web interface, modular frame design

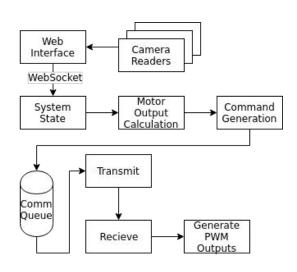




TECHNICAL DIAGRAMS



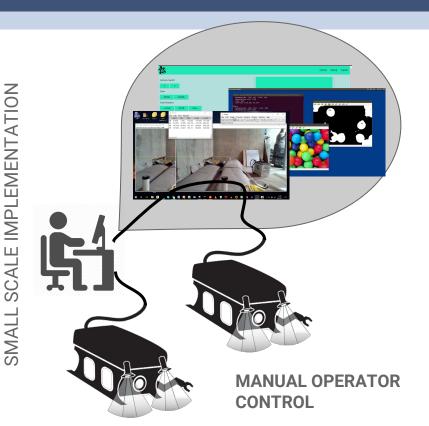
(above): IDW Diagram of Archelon ROV



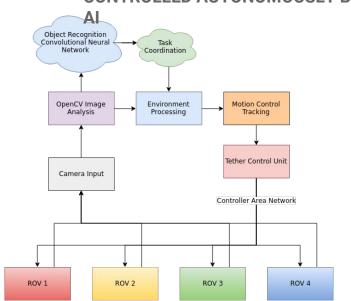
(above): Flowchart Diagram of Control System



IMPLEMENTATION



CONTROLLED AUTONOMOUSLY BY



IMPLEMENTATION

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TIMELINE

Aug. 2017

Dec. 2017

May 2018

April 2019

Dec. 2019

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Concepting

Committed, skilled and

balanced founding team.

Commitment

Complete development of ROV product, create and finalize diagram for implementation of ROVs.

Validation

Continue to attract additional resources for equity or future revenues. Looking for clear market validation (Product Market Fit) to move onto scaling.

Scaling

Show clear, growing and measurable user/market traction in big or rapidly growing target market.

Establishing

Achieve strong and continued growth trajectory. Continue to gain access to resources.

meaningful target with clear direction for min. 2 years.

Have a clear and



THANKS!

Any questions?

You can find us at our website:

https://ascendtech4h.org/